

GE Industrial Systems

VTUR Turbine Control Board

These instructions do not purport to cover all details or variations in equipment, nor to provide for every possible contingency to be met during installation, operation, and maintenance. The information is supplied for informational purposes only, and GE makes no warranty as to the accuracy of the information included herein. Changes, modifications, and/or improvements to equipment and specifications are made periodically and these changes may or may not be reflected herein. It is understood that GE may make changes, modifications, or improvements to the equipment referenced herein or to the document itself at any time. This document is intended for trained personnel familiar with the GE products referenced herein.

GE may have patents or pending patent applications covering subject matter in this document. The furnishing of this document does not provide any license whatsoever to any of these patents. All license inquiries should be directed to the address below. If further information is desired, or if particular problems arise that are not covered sufficiently for the purchaser's purpose, the matter should be referred to:

GE Industrial Systems Post Sales Service 1501 Roanoke Blvd. Salem, VA 24153-6492 USA Phone: + 1 888 GE4 SERV (888 434 7378, United States) + 1 540 378 3280 (International) Fax: + 1 540 387 8606 (All)

("+" indicates the international access code required when calling from outside the USA)

This document contains proprietary information of General Electric Company, USA and is furnished to its customer solely to assist that customer in the installation, testing, operation, and/or maintenance of the equipment described. This document shall not be reproduced in whole or in part nor shall its contents be disclosed to any third party without the written approval of GE Industrial Systems.

GE PROVIDES THE FOLLOWING DOCUMENT AND THE INFORMATION INCLUDED THEREIN AS IS AND WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO ANY IMPLIED STATUTORY WARRANTY OF MERCHANTABILITY OR FITNESS FOR PARTICULAR PURPOSE.

Issue date: 2002-06-30

© 2002 by General Electric Company, USA. All rights reserved.

Section	Page
Functional Description	2
Installation	
Operation	6
Features	
Specifications	
Diagnostics	9
Automatic Synchronizing	
Configuration	12
TRPG Primary Trip Terminal Board	15
Installation	16
Operation	
Features	
Diagnostics	
Configuration	
DTRT Trip Transition Board	
Installation	21
DTUR Pulse Rate Terminal Board	22
Installation	23
I/O Board Alarms	24

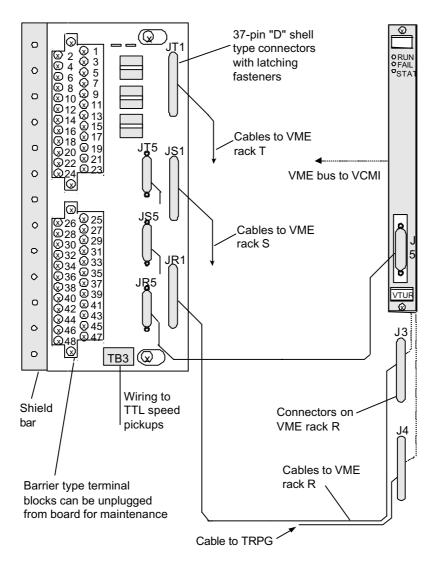
Functional Description

The turbine control board, VTUR controls three primary overspeed trip solenoids and automatic synchronizing. It also interfaces to four passive pulse rate devices, and monitors shaft voltage and current. The speed signal cable to VTUR uses the J5 plug on the front of the board, and the other signals use the J3 connector on the VME rack. Terminal board TTUR provides simplex signals through the JR connector, and fans out TMR signals to the JR, JS, and JT connectors. J4 on the VME rack connects to the TRPG terminal board described in the Primary Trip section.

A two-slot version of this board (VTURH2) is available for driving six trip solenoids using two TRPG boards. VTURH2 only accepts eight flame detectors.

TTURH1B Terminal Board

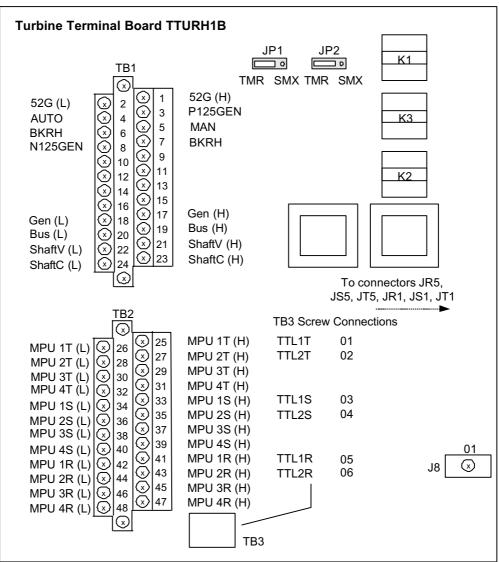
VTUR VME Board



Turbine Control Terminal Board, Processor Board, and Cabling

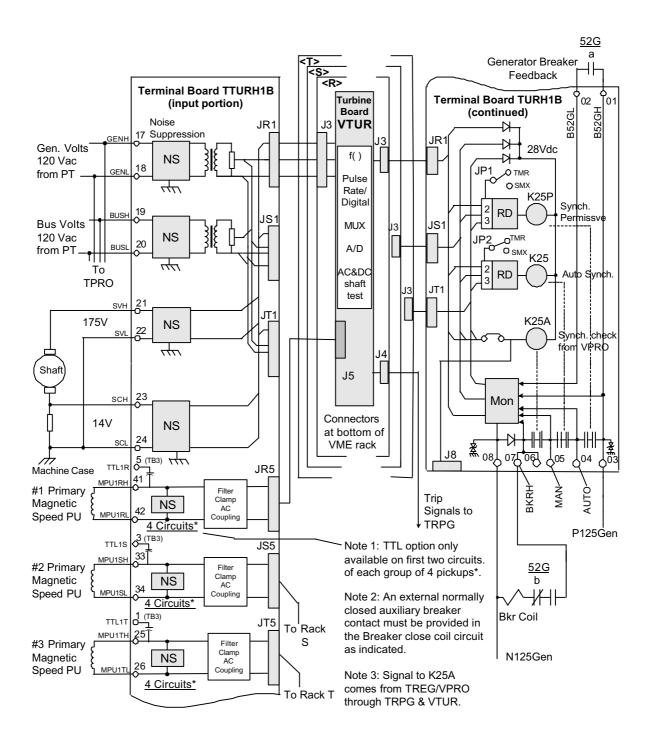
Installation

Magnetic pick ups, shaft pick ups, potential transformers, and breaker relays are wired to two I/O terminal blocks on TTUR. Each block is held down with two screws and has 24 terminals accepting up to #12 AWG wires. A shield termination strip attached to chassis ground is located immediately to the left of each terminal block. Jumpers JP1 and JP2 select either SMX or TMR for relay drivers K25 and K25P. TB3 is for optional TTL connections to active speed pickups; these require an external power supply.



TTUR Terminal Board

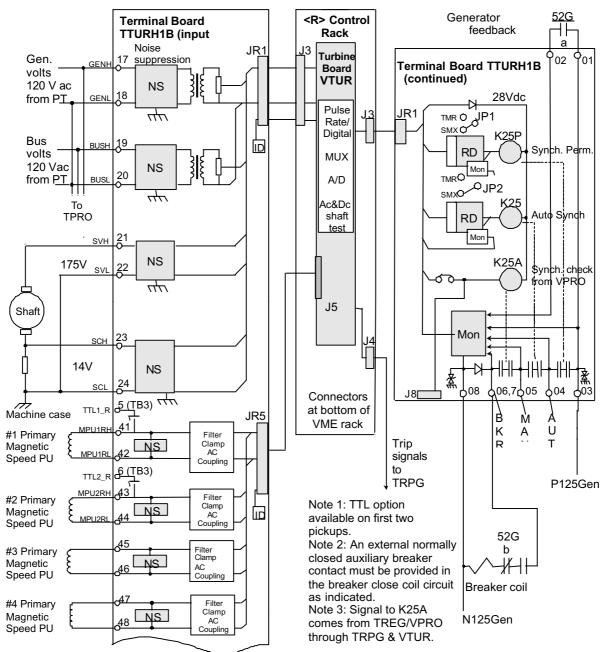
All three relays have two normally open contacts in series with the breaker close coil. In TMR applications all inputs fan to the three control racks. Control signals coming into TTUR from R, S, and T are voted before they actuate permissive relays K25 and K25P. Relay K25A is controlled by the VPRO and TREG boards.



Turbine Control Inputs, Synchronizing, and Primary Trip Interface, TMR

Operation

Pulse rate to digital circuits are on the VTUR board. VTUR alarms high voltages and tests the integrity and continuity of the circuitry. In the simplex application, up to four pulse rate signals may be used to measure turbine speed. Generator and bus voltages are brought into VTUR for automatic synchronizing in conjunction with the turbine controllerand excitation system. TTUR has permissive generator synchronizing relays and controls the main breaker relay coil 52G. Shaft voltage is picked up with brushes and monitored along with the current to the machine case.



Turbine Control Inputs, Synchronizing, and Primary Trip Interface, Simplex

Features

The median speed signal is used for speed control and for the primary overspeed trip signal.

A metal oxide varister (MOV) and a current limiting resistor are used in each circuit. An interface is provided for four passive, magnetic speed inputs with a frequency range of 2 - 20,000 Hz. Using passive pickups on a 60-tooth wheel, circuit sensitivity allows detection of 2 rpm turning gear speed to determine if the turbine is stopped (zero speed). If automatic turning gear engagement is provided in the turbine control, this signal initiates turning gear operation.

The primary overspeed trip calculations are performed in the controllerusing algorithms similar to (but not the same as) those shown in the section on the VPRO Protection Module. The fast trip option used on gas turbines runs in VTUR and is described below.

The normal primary overspeed trip is calculated in the controller and passed to the VTUR and then to the TRPG terminal board. TRPG contains magnetic relays for interface with the electrical trip devices (ETDs). TRPG works in conjunction with the TREG board to form the *Primary* and *Emergency* sides of the interface to the ETDs. Usually this applies to turbines which do not have a mechanical overspeed bolt and require a separate emergency overspeed (EOS) system. Three ETDs can be driven from each TRPG/TREG combination with the positive side of each solenoid connected to the TREG and the negative side connected to the TRPG.

Two different versions of the TRPG are available, with version 1 used for triple redundant (TMR) systems and version 2 used for Simplex systems. The only difference is that the TMR version has three voting relays per ETD circuit and the Simplex version has one relay per circuit. The VTUR board monitors the current flowing in its relay driver control line to determine its energize or de-energize vote/status of the relay coil. A normally closed contact from each relay on the TRPG board is monitored by the diagnostics to determine its proper operation.

Bearings can be damaged by the flow of electrical current from the shaft to the case. This current can occur for several reasons.

- A static voltage can be caused by droplets of water being thrown off the last stage buckets in a steam turbine. This voltage will build up until a discharge occurs through the bearing oil film.
- An ac ripple on the dc generator field can produce an ac voltage on the shaft with respect to ground through the capacitance of the field winding and insulation. Note that both of these sources are weak, so high impedance instrumentation is used to measure these voltages with respect to ground.
- A voltage may be generated between the ends of the generator shaft due to dissymmetries in the generator magnetic circuits. If the insulated bearings on the generator shaft break down, the current will flow from one end of the shaft through the bearings and frame to the other end. Brushes can be used to discharge damaging voltage buildup, and a shunt should be used to monitor the current flow.

The turbine control continuously monitors the shaft to ground voltage and current, and alarms excessive levels. There is an ac test mode and a dc test mode. The ac test applies an ac voltage to test the integrity of the measuring circuit.

The dc test checks the continuity of the external circuit, including the brushes, turbine shaft, and the interconnecting wire.

Note The dc test is driven from the <R> controller only. If the <R> controller is down, this test cannot be run successfully.

Specifications

Item	Specification
Number of inputs	TTUR: 12 passive speed pickups 1 shaft voltage and 1 shaft current measurement 1 generator and 1 bus voltage Generator breaker status contact
	VTUR: 4 passive speed pickups 1 shaft voltage and 1 current measurement 1 generator and 1 bus voltage Generator breaker status 8 flame detectors from first TRPG
Number of outputs	TTUR: Generator breaker coil, 5A at 125 V dc
	VTUR: Automatic synchronizing Primary trip solenoid interface, 3 outputs to TRPG Additional 3 trip outputs from second TRPG using VTURH2
Trip solenoids (TRPG)	Solenoids draw up to 1 A at 125 V dc and have a time constant of $L/R = 0.1$ sec.
Power supply voltage	TTUR: Nominal 125 V dc to breaker coil
MPU pulse rate range	2 Hz to 20 kHz
MPU pulse rate accuracy	0.05% of reading
MPU input circuit sensitivity	27 mV pk (detects 2 rpm speed)
Shaft voltage monitor	Signal is frequency of \pm 5 V dc (0 – 1 MHz) pulses from 0 to 2,000 Hz
Shaft voltage wiring	Up to 300 m (984 ft), with maximum two-way cable resistance of 15 ohms
Shaft voltage dc test	Applies a 5 V dc source to test integrity of the external turbine circuit and measures dc current flow. Circuit computes a differential resistance between 0 and 150 ohms within \pm 5 ohms and compares against shunt limit and brush limit. Readings above 50 ohms indicate a fault. Return signal is filtered to provide 40 dB of noise attenuation at 60 Hz.
Shaft voltage ac test	Applies a test voltage of 1 kHz to the input of the VTUR shaft voltage circuit (R module only). Shaft voltage monitor circuit on R, S, and T displays an offset of 1000 Hz from normal reading.
Shaft current input	Measures shaft current in amps ac (shunt voltage up to 0.1 V pp)
Generator and bus voltage sensors	Two single phase potential transformers, with secondary output supplying a nominal 115 V rms Each input has less than 3 VA of loading. Allowable voltage range for synch is 75 to 130 V rms. Each PT input is magnetically isolated with a 1,500 V rms barrier. Cable length can be up to 1,000 ft. of 18 AWG wiring.
Synchronizing measurements	Frequency accuracy 0.05% over 45 to 66 Hz range. Zero crossing of the inputs is monitored on the rising slope. Phase difference measurement is better than \pm 1 degree.
Generator breaker circuits (synchronizing)	External circuits should have a voltage range within 20 to 140 V dc. The external circuit must include a NC breaker auxiliary contact to interrupt the current. Circuits are rated for NEMA class E creepage and clearance. 250 V dc applications require interposing relays.
Contact voltage sensing	20 V dc indicates high and 6 V dc indicates low. Each circuit is optically isolated and filtered for 4 ms.

Diagnostics

Diagnostic information includes feedback from the solenoid relay driver and contact, high flame detector voltage, slow synch check relay, slow auto synch relay, and locked up K25 relay. If any one of the signals goes unhealthy, a composite diagnostic alarm L3DIAG_VTUR occurs. The diagnostic signals can be individually latched and then reset with the RESET_DIA signal if they go healthy.

Terminal board connectors JR1, JS1, JT1, JR5, JS5, JT5 have their own ID device which is interrogated by the I/O board. The ID device is a read-only chip coded with the terminal board serial number, board type, revision number, and plug location.

Automatic Synchronizing

All synchronizing connections are located on the TTUR terminal board. The generator and bus voltages are supplied by two, single phase, potential transformers (PTs) with a fused secondary output supplying a nominal 115 V rms. Measurement accuracy between the zero crossing for the bus and generator voltage circuits is 1 degree.

Turbine speed is matched against the bus frequency, and the generator and bus voltages are matched by adjusting the generator field excitation voltage from commands sent between the turbine controller and the EX2000 over the Unit Data Highway (UDH). A command is given to close the breaker when all permissives are satisfied, and the breaker is predicted to close within the calculated phase/slip window. Feedback of the actual breaker closing time is provided by a 52G/a contact from the generator breaker (not an auxiliary relay) to update the data base. An internal K25A synch check relay is provided on the TTUR; the independent backup phase/slip calculation for this relay is performed in the <P> Protection Module. Diagnostics monitor the relay coil and contact closures to determine if the relay properly energizes or de-energizes upon command.

Synchronizing Modes

There are three basic synchronizing modes. Traditionally, these modes are selected from a generator panel mounted selector switch:

- **Off** The breaker will not be closed by the Mark VI control. The check relay will not pickup.
- **Manual** The operator initiates breaker close, which is still subject to the K25A Synch Check contacts driven by VPRO. The manual close is initiated from an external contact on the generator panel, normally connected in series with a *Synch Mode in Manual* contact.
- Auto The system will automatically match voltage and speed, and then close the breaker at the right time to hit top dead center on the synchroscope. All three of the following functions must agree for this closure to occur:
 - **K25A** synch check relay, checks the allowable slip/phase window, from VPRO.
 - **K25** auto synch relay, provides precision synchronization, from VTUR.
 - **K25P** synch sequence permissive, checks the turbine sequence status, from VTUR.

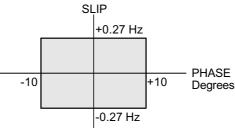
Details of the various checks are discussed in the following sections.

Synch Check

The K25A synch check function is based on phase lock loop techniques. The calculations for this function are done in the VPRO, but interfaces to the Breaker close circuit on the TTUR board. It performs limit checks against adjustable constants as follows:

- Generator undervoltage
- Bus undervoltage
- Voltage error
- Frequency error (slip), with a maximum value of 0.33 Hz, typically set to 0.27 Hz
- Phase error with a maximum value of 30 degrees, typically set to 10 degrees

In addition, synch check arms logic to enable the function and provides bypass logic for deadbus closure. The synch window is based on typical settings:

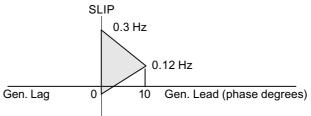


Typical Synch Window

Auto Synch

The Auto Synch K25 function uses zero voltage crossing techniques. It compensates for the breaker time delay, which is defined by two adjustable constants with logic selection between the two (for two breaker applications). The calculations, which are done on the VTUR board, include phase, slip, acceleration, and anticipated time lead for the breaker delay. Based on the measured breaker close time, the time delay parameter is adjusted, up to certain limits.

In addition, auto synch arms logic to enable the function and bypasses logic to provide for deadbus or manual closure. The auto synch projected synch window is where positive slip indicates the generator frequency is higher than the bus frequency.





The projected window is based on current phase, current slip, and current acceleration. The generator must currently be lagging and have been lagging for the last 10 consecutive cycles, and projected (anticipated) to be leading when the breaker actually reaches closure. Auto synch will not allow the breaker to close with negative slip; speed matching typically aims at around +0.12 Hz slip.

Synchronization Display

A special synchronization screen is available on the HMI with a real-time graphical phase display and control pushbuttons. The display items are listed in the following table.

Synch Display	Description	
Dynamic parameters	Voltages: Frequencies: Phase:	Generator, bus, difference Generator, bus, slip (difference) Difference angle, degrees
Status indication	Mode: Synch OFF, M Synch monitor: Dead bus breaker: Second breaker if ap Synch permissive: Auto synch enabled Speed adjust: Voltage adjust:	OFF, ON Open/close
Synch permissives	Generator voltage: Bus voltage: Generator frequency: Bus frequency: Difference volts: Difference frequency: Phase:K25 K25A	OK/not OK OK/not OK
Limit constants	Upper and lower limit	s for the above permissives
Breaker performance	Diagnostics:	Slow check relay Synch relay lockup Breaker #1 close time out of limits Breaker #2 close time out of limits Relay K25P trouble Breaker closing voltage (125 V dc) missing
Control pushbuttons	Synch monitor: Speed adjust: RAISE Voltage adjust:	ON, OFF , LOWER RAISE, LOWER

Synchronizing Display Items

Configuration

The following table defines the configuration choices and defaults. For details refer to GEH-6403, *Control System Toolbox for Configuring the Mark VI Turbine Controller. Typical VTUR Configuration*

Parameter	Description	Choices
Configuration		
VTUR system limits	Select system limits	Enable, disable
SMredundancy	Select Simplex or TMR system	Simplex or TMR
AccelCalType	Select acceleration calculation type	Slow, medium, fast
FastTripType	Select Fast Trip algorithm	Unused, PR_Single, PR_Max
J3J5:IS200TTURH1A	TTUR connected to VTUR through J3 and J5	Connected, not connected
PulseRate1	Pulse rate input 1 - board point	Point edit (input FLOAT)
PRType	Select Speed or Flow type input	Unused, speed, flow, Speed_LM
PRScale	Select pulses per revolution	0 to 1,000
SysLim1Enable	Select system limit 1	Enable, disable
SysLim1Latch	Select whether alarm will latch	Latch, not latch
SysLim1Type	Select type of alarm initiation	>= or <=
SysLimit1	Select alarm level in GPM or RPM	0 to 20,000
SysLim2Enable	Select system limit 2 (as above)	Enable, disable
TMRDiffLimit	Difference limit for voted PR inputs EU	0 to 20,000
ShVoltMon	Shaft voltage monitor - board point	Point edit (input FLOAT)
SysLim1Enable	Select System Limit 1	Enable, disable
SysLim1Latch	Select whether alarm will latch	Latch, not latch
SysLim1Type	Select type of alarm initiation	>= or <=
SysLimit1	Select alarm level in frequency	0 to 100
SysLim2Enable	Select system limit 2 (as above)	Enable, disable
ShCurrMon	Shaft current monitor - board point	Point edit (input FLOAT)
ShuntOhms	Shunt resistance	0 to 100
Shunt limit	Shunt maximum ohms	0 to 100
Brush limit	Shaft brush maximum ohms	0 to 100
SysLim1Enable	Select system limit 1	Enable, disable
SysLim1Latch	Select whether alarm will latch	Latch, not latch
SysLim1Type	Select type of alarm initiation	>= or <=
SysLimit1	Select alarm level in amps	0 to 100

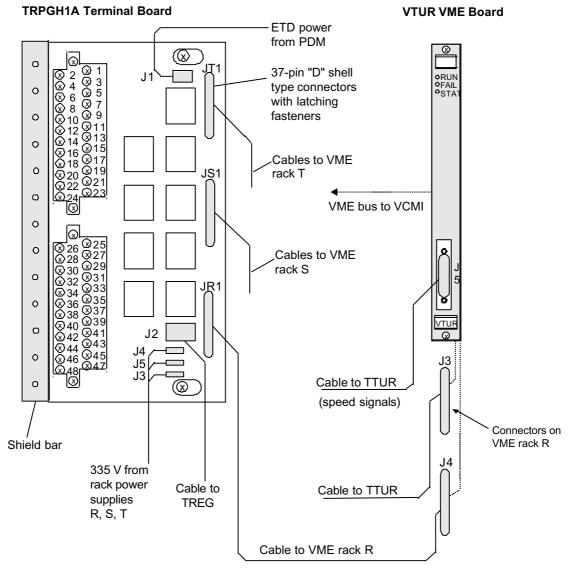
S	ysLim2Enable	Select system limit 2	Enable, di	isable	
-	enPT_KVolts	Generator potential transfomer - board point	Point edit	(input FLC	DAT)
PT_Input PT_Output		PT input in kVrms for PT output	0 to 1,000		
		PT output in Vrms, nominal 115 V rms	0 to 150		
Sy	ysLim1	Select alarm level in kVrms	0 to 1,000)	
Sy	ysLim2	Select alarm level in kVrms	0 to 1,000)	
В	usPT_Kvolts	Bus potential transformer - board point	Point edit	(input FLC	DAT)
CI	kt_Bkr	Circuit breaker - board point	Point edit	(input BIT	-)
Sy	ystem Frequency	Select frequency in Hz	50 or 60		
CI	B1CloseTime	Breaker 1 closing time, ms	0 to 1,000)	
CI	B1 AdaptLimit	Breaker 1 self adaptive limit, ms	0 to 1,000)	
CI	B1 AdaptEnabl	Select breaker 1 self adaptive limit	Enable, di	isable	
	CB1FreqDiff	Breaker 1 special window frequency difference, Hz	0 to 10		
	CB1PhaseDiff	Breaker 1 special window phase difference, degrees	0 to 30		
CI	B2CloseTime	Breaker 2 closing time, ms (as above)	0 to 1,000)	
J4:IS200	TRPGH1A	TRPG terminal board, 8 flame detectors	Connecte	d, not conn	ected
Board Points Signals		Description – Point Edit (Enter Signal Connection)	Dir	rection	Туре
L3	3DIAG_VTUR1	Board diagnostic	Inp	out	BIT
L3	3DIAG_VTUR2	Board diagnostic	Inp	out	BIT
L3	3DIAG_VTUR3	Board diagnostic	Inp	out	BIT
Sł	hShntTst_OK	Shaft voltage monitor shunt test OK	Inp	out	BIT
Sł	hBrshTst_OK	Shaft voltage brush test OK	Inp	out	BIT
CI	B_Volts_OK	L3BKR_VLT circuit breaker coil voltage available	Inp	out	BIT
CI	B_K25P_PU	L3BKR_PERM sync permissive relay picked up	Inp	out	BIT
CI	B_K25_PU	L3KBR_GES auto sync relay picked up	Inp	but	BIT
CI	B_K25A_PU	L3KBR_GEX sync check relay picked up	Inp	out	BIT
G	en_Sync_LO	Generator sync trouble (lockout)	Inp	out	BIT
L2	25_Command		Inp	out	BIT
Ko	q1_Status		Inp	out	BIT
	:	:	Inp	out	BIT
Ko	q6_Status		Inp	out	BIT
F	D1_Flame		Inp	but	BIT
	:	:	Inp	out	BIT
	D16_Flame		Inp		BIT
Sy	ysLim1PR1		Inp		BIT
	:	:	Inp		BIT
Sy	ysLim1PR4		Inp	out	BIT

SysLim1SHVAc shaft voltage frequency high L30TSVHInputBITSysLim1SHCAc shaft current high L30TSCHInputBITSysLim1GENInputBITSysLim1BUSInputBITSysLim2PR1(same set as for Limit1 above)InputBITGenFreqHz frequencyInputFLOATBusFreqHz frequencyInputFLOATGenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATAccel4RPM/SECInputFLOATFImDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
SysLim1GENImputBITSysLim1BUSImputBITSysLim2PR1(same set as for Limit1 above)InputBITGenFreqHz frequencyInputFLOATBusFreqHz frequencyInputFLOATGenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATAccel4RPM/SECInputFLOATFlimDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
SysLim1BUSInputBITSysLim2PR1(same set as for Limit1 above)InputBITGenFreqHz frequencyInputFLOATBusFreqHz frequencyInputFLOATGenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
SysLim2PR1(same set as for Limit1 above)InputBITGenFreqHz frequencyInputFLOATBusFreqHz frequencyInputFLOATGenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
BusFreqHz frequencyInputFLOATGenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-GenLag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATi::InputFLOATAccel4RPM/SECInputFLOATFImDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
GenVoltsDiffKiloVolts rms-GenLow is negativeInputFLOATGen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOATi::InputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
Gen Freq DiffSlip Hz-GenSlow is negativeInputFLOATGen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOAT:::InputFLOATAccel4RPM/SECInputFLOATFImDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
Gen Phase DiffPhase Degrees-Gen Lag is negativeInputFLOATCB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOAT:::InputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
CB1CloseTimeBreaker #1 close time in millisecondsInputFLOATCB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOAT:::InputAccel4RPM/SECInputFLOATFImDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
CB2CloseTimeBreaker #2 close time in millisecondsInputFLOATAccel1RPM/SECInputFLOAT::InputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
Accel1RPM/SECInputFLOAT::InputFLOATAccel4RPM/SECInputFLOATFImDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
:InputFLOATAccel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
Accel4RPM/SECInputFLOATFlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
FlmDetPwr1335 V dcInputFLOATShTestACL97SHAFT_AC SVM_AC_TESTOutputBIT
ShTestAC L97SHAFT_AC SVM_AC_TEST Output BIT
ShTestDC L97SHAFT_DC SVM_DC_TEST Output BIT
FD1_Level1 = high detection counts levelOutputBIT
: Output BIT
FD16_Level1 = high detection counts levelOutputBIT
Sync_Perm_AS L83AS - auto sync permissive Output BIT
Sync_Perm L25P - sequencing sync permissive Output BIT
Sync_Monitor L83S_MTR - monitor mode Output BIT
Sync_Bypass1 L25_BYP-1 = auto aync bypass Output BIT
Sync_Bypass0L25_BYPZ-0 = auto sync permissiveOutputBIT
CB2_Selected L43SAUT2 - 2nd breaker selected Output BIT
AS_Win_Sel L43AS_WIN - special window selected Output BIT
Sync_Reset L86MR_SYNC - sync trouble reset Output BIT
Kq1L20PTR1 - primary trip relayOutputBIT
: Output BIT
Kq6L20PTR6 - primary trip relayOutputBIT

TRPG Primary Trip Terminal Board

The TRPG terminal board contains nine magnetic relays to interface with three trip solenoids, known as the Electrical Trip Devices (ETD). The TRPG works in conjunction with the TREG to form the *Primary* and *Emergency* sides of the interface to the ETDs. The H1A version for TMR applications has three voting relays per trip solenoid. The H2A version for simplex applications has one relay per trip solenoid. TRPG also accommodates eight Geiger Mueller flame detectors.

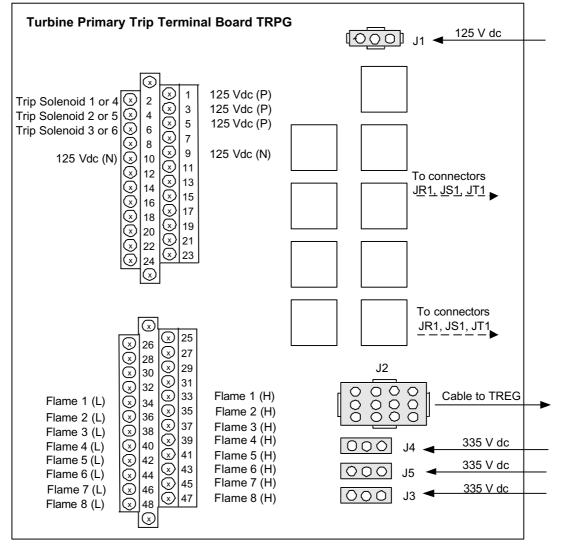
An optional double-width VTURH2A board can be cabled to a second TRPG board for interface to three additional ETDs, but **no** additional flame detectors.



TRPG Terminal Board, I/O Board and Cabling

Installation

The three trip solenoids are wired directly to the first I/O terminal block and the flame detectors (if used) to the second terminal block. Power to the flame detectors is wired to J3, J4, and J5.



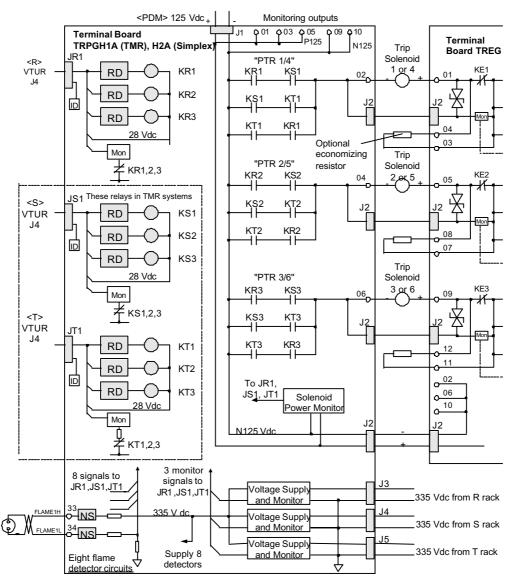
Up to two #12 AWG wires per point with 300 V insulation

Terminal blocks can be unplugged from terminal board for maintenance

TRPG Terminal Board Wiring

Operation

VTUR provides the primary trip function by controlling the relays on TRPG, which trip the main protection solenoids. In TMR applications, the three inputs are voted in hardware using a relay ladder logic two-out-of-three voting circuit. Relay coil currents, contact status, and supply voltages are monitored for diagnostic purposes.



TRPG and Trip Solenoids

Features

VTUR controls the main breaker through TTUR and three trip solenoids through TRPG. With a second TRPG, six trip solenoids can be controlled. In addition, VTUR handles shaft speed, generator voltage, and bus voltage inputs from TTUR, plus up to eight flame detector inputs from one TRPG board.

Control Of Trip Solenoids

Both TRPG and TREG control the trip solenoids so that either one can remove power and close the steam or fuel valves. TRPG holds nine relays in three voting groups of three, one group for each trip solenoid. Voltage for the relay coils is supplied from the R, S, and T rack backplane. The trip solenoids are supplied with power through plug J1. A metal oxide varistor (MOV) for current suppression is on TREG, and an optional economizing current limiting resistor can be wired to the TREG terminals.

Flame Detectors

Up to eight flame detectors can be used for gas turbine applications. The detectors are supplied with 335 V dc, 0.5 mA through plugs J3, J4, and J5.

With no flame present, the detector charges up to the supply voltage, but presence of the flame causes the detector to charge to a level and then discharge through the TRPG board. As the flame intensity increases the discharge frequency increases. When the detector discharges, VTUR and TRPG convert the discharged energy into a voltage pulse. The pulse rate varies from 0 to 1,000 pulses/sec. These voltage pulses are fanned out to all three modules. *TRPG Specification*

Specification
3 solenoids per TRPG (total of 6 per VTUR)
125 V dc standard with up to 1 A draw 24 V dc is alternate with up to 1 A draw
L/R time constant is 0.1 sec
Metal oxide varister (MOV) on TREG
Terminals for optional 10 ohm, 70 watt economizing resistor
Relays supplied with 28 V dc from R, S, and T racks
8 detectors per TRPG (total of 8 per VTUR)
335 V dc with 0.5 mA per detector

Diagnostics

The ID device is a read-only chip coded with the terminal board serial number, board type, revision number, and the plug location Descriptions of the TRPG diagnostics are listed under VTUR. The diagnostics include feedback from the trip solenoid relay driver and contact, solenoid power bus, and the flame detector excitation voltage too low or too high.

Connectors JR1, JS1, and JT1 on the terminal board have their own ID device, which is interrogated by the I/O board.

In Simplex systems, TRPGH2 is used. This board has one relay per ETD circuit instead of three and is controlled by only one VTUR board.

Voltage pulses above 2.5 volts generate a logic high, and the pulse rate over a 40 ms time period is measured in a counter.

Configuration

Like all I/O boards, the TRPG board is configured using the toolbox. This software usually runs on a data-highway connected CIMPLICITY station or workstation. The following table defines the configuration choices. For details refer to GEH-6403, *Control System Toolbox for Configuring the Mark VI Turbine Controller*.

Typical TRPG Configuration

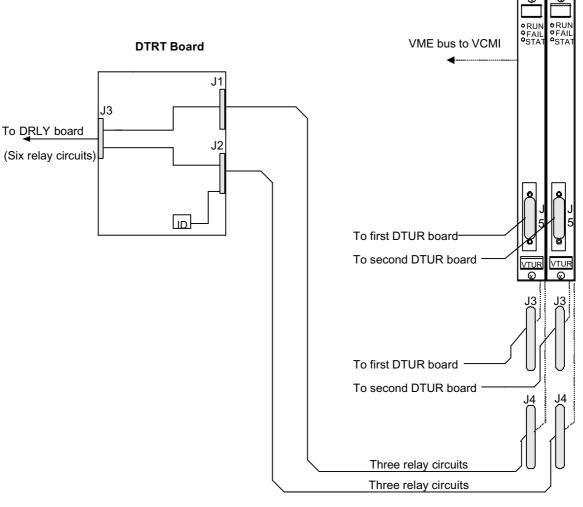
Parameter	Description	Choices	
Configuration			
J4:IS200TRPGH1A	First TRPG terminal board	Connected, not con	nected
FlameInd1	Intensity (Hz), flame detector number 1 - board point	Point edit (input FL	OAT)
FImDetTime	Flame detector time interval	0.04, 0.08, 0.16 sec	:
FlameLimitHI	Flame threshold limit HI (HI detection cnts means LOW sensitivity)	0 to 160	
FlameLimitLOW	Flame threshold limit LO (LOW detection cnts means HI sensitivity)	0 to 160	
Flame_Det	Flame detector selected	Used, unused	
FlameIndN	Flame detectors 2 through 8 as above - board point	Point edit (input FL	OAT)
Kq1_Status	Primary trip relay status, first of 3 PTRs - board point	Point edit (input BIT	-)
Kq1	Primary trip relay, first of three PTR - board point	Point edit (output B	IT)
PTR_Output	Primary trip relay - used/unused	Used, unused	
J4A:IS200TRPGH1A	Second TRPG board for expanded VTUR, with three more trip solenoid outputs, and flame detectors 9 through 16 (not used)	Connected, not con	nected
Board Points Signals	Description – Point Edit (Enter Signal Connection)	Direction	Туре
FlameInd1	Intensity (Hz)	Input	FLOAT
:	Intensity (Hz)	Input	FLOAT
FlameInd8	Intensity (Hz)	Input	FLOAT

DTRT Trip Transition Board

Only the simplex version of this board is available.

The DTRT board is a DIN-rail mounted trip transition board that interfaces the VTUR board with the DRLY board. DTRT allows up to six trip functions on the VTUR to interface with DRLY, instead of the normal TRPG board. Two VTUR boards can be connected to the DTRT to control a total of six relays on DRLY. DTRT transfers board identification from the ID chip on DRLY to VTUR for diagnostic purposes. DTRT has its own ID chip connected to J2.

DTRT must be used in all applications where trips from VTUR to DRLY are required. DTRT cannot be eliminated if the application requires only one VTUR. Three 37-pin D connectors for the three cables are provided. A high density Euro-Block type terminal block is permanently mounted to the board with three screw connections for the ground connection (SCOM).



VTUR Boards

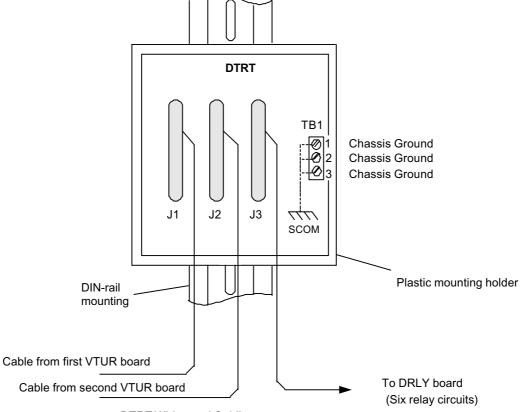
DTRT Board

Installation

There is no shield termination strip with this design.

The DTRT board slides into a plastic holder, which mounts on the DIN-rail. The three cables connecting VTUR and DRLY plug into the 37-pin D type connector. The first three DRLY circuits are driven by the VTUR connected to J1, and the second three DRLY circuits are driven by the VTUR connected to J2. Three screws are provided on terminal block TB1 for the SCOM (ground) connection, which should be as short a distance as possible.

DTRT must be used in all applications where trips from VTUR to DRLYs are required. DTRT is still required if the application only requires one VTUR.



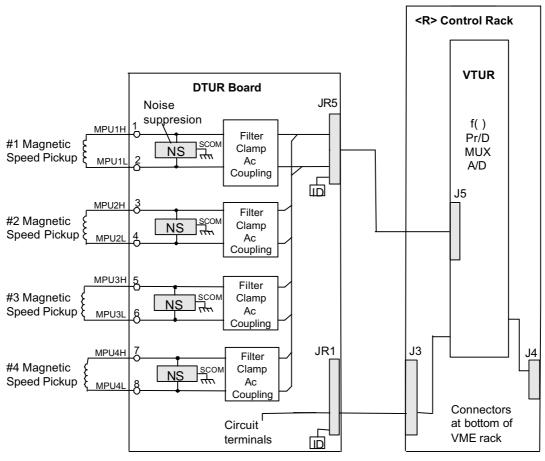
DTRT Wiring and Cabling

DTUR Pulse Rate Terminal Board

Only the simplex version is available.

The DTUR board is a compact pulse-rate terminal board, designed for DIN-rail mounting. The board accepts four passive pulse-rate transducers (magnetic pickups) for speed and flow measurement. It connects to the VTUR processor board with a 37-pin cable and a 15-pin cable. These cables are identical to those used on the larger TTUR terminal board. DTUR boards can be stacked vertically on the DIN-rail to conserve cabinet space. VTUR only accommodates one DTUR board.

DTUR has onboard pulse rate signal conditioning identical to that on the TTUR. High density Euro-Block type terminal blocks are permanently mounted to the board with two screws for the ground connection (SCOM). Two on-board ID chips identify the connectors and board to VTUR for system diagnostic purposes.

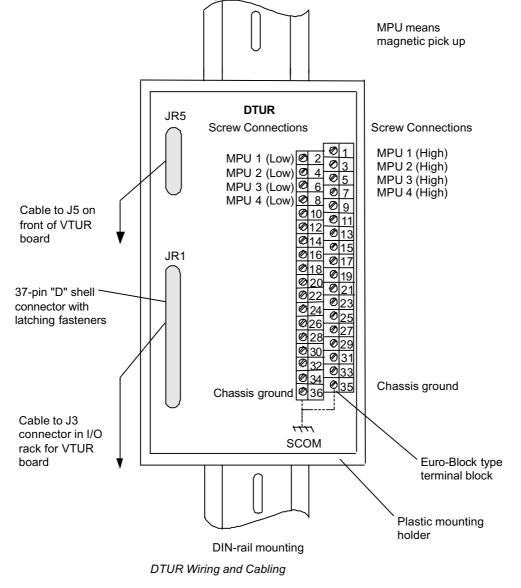


DTUR Board

Installation

There is no shield termination strip with this design.

The DTUR board slides into a plastic holder, which mounts on the DIN-rail. The magnetic pickups are wired directly to the terminal block which has 36 terminals. Typically #18 AWG shielded twisted pair wiring is used. There are two screws for the SCOM (ground) connection, which should be as short a distance as possible.



I/O Board Alarms

Diagnostic alarms for any I/O board can be displayed and reset from the toolbox. For troubleshooting and general diagnostic alarm information refer to GEH-6421 Volume I, Chapter 8.

I/O Board Diagnostic Alarms

Board	Fault	Fault Description	Possible Cause
VTUR	2	Flash Memory CRC Failure	Board firmware programming error (board will not go online)
	3	CRC failure override is Active	Board firmware programming error (board is allowed to go online)
	16	System Limit Checking is Disabled	System checking was disabled by configuration
	17	Board ID Failure	Failed ID chip on the VME I/O board
	18	J3 ID Failure	Failed ID chip on connector J3, or cable problem
	19	J4 ID Failure	Failed ID chip on connector J4, or cable problem
	20	J5 ID Failure	Failed ID chip on connector J5, or cable problem
	21	J6 ID Failure	Failed ID chip on connector J6, or cable problem
	22	J3A ID Failure	Failed ID chip on connector J3A, or cable problem
	23	J4A ID Failure	Failed ID chip on connector J4A, or cable problem
	24	Firmware/Hardware Incompatibility	Invalid terminal board connected to VME I/O board
	30	ConfigCompatCode mismatch; Firmware: #; Tre: # The configuration compatibility code that the firmware is expecting is different than what is in the tre file for this board	A tre file has been installed that is incompatible with the firmware on the I/O board. Either the tre file or firmware must change. Contact the factory.
	31	IOCompatCode mismatch; Firmware: #; Tre: # The I/O compatibility code that the firmware is expecting is different than what is in the tre file for this board	A tre file has been installed that is incompatible with the firmware on the I/O board. Either the tre file or firmware must change. Contact the factory.
	32-37	Solenoid # Relay Driver Feedback Incorrect. Solenoid (1- 6) relay driver feedback is incorrect as compared to the command; VTUR cannot drive the relay correctly until the hardware failure is corrected	The solenoid relay driver on the TRPG/L/S board has failed, or the cabling between VTUR and TRPG/L/S is incorrect.
	38-43	Solenoid # Contact Feedback Incorrect. Solenoid (1-6) relay contact feedback is incorrect as compared to the command; VTUR cannot drive the relay correctly until the hardware failure is corrected	The solenoid relay driver or the solenoid relay on the TRPG/L/S board has failed, or the cabling between VTUR and TRPG/L/S is incorrect.

44-45	TRPG # Solenoid Power Absent. P125/24 V dc power is not present on TRPG terminal board; VTUR cannot energize trip solenoids 1 through 3, or 4 through 6 until power is present	Power may not be coming into TRPG/L/S on the J1 connector, or the monitoring circuit on TRPG/L/S is bad, or the cabling between TRPG/L/S and VTUR is at fault.
46,48	TRPG # Flame Detector Volts Low at Y Volts. TRPG 1 or 2 flame detect voltage is low; the ability to detect flame by detectors 1 through 8, or 9 through 16 is questionable	Power comes into TRPG via J3, J4, and J5. If the voltage is less than 314.9 V dc, this should be investigated. If the voltage is above this value, the monitoring circuitry on TRPG or the cabling between TRPG and VTUR is suspect.
47,49	TRPG # Flame Detector Volts High at Y Volts. TRPG 1 or 2 flame detect voltage is high; the ability to detect flame by detectors 1 through 8, or 9 through 16 is questionable because the excitation voltage is too high and the devices may be damaged	This power comes into TRPG via J3, J4, and J5. If the voltage is greater than 355.1 V dc, this should be investigated. If the voltage is below this value, the monitoring circuitry on TRPG or the cabling between TRPG and VTUR is suspect.
50	L3BKRGXS – Synch Check Relay is Slow. The auto synchronization algorithm has detected that during synchronization with no dead bus closure (synch bypass was false) the auto synch relay I3BKRGES closed before synch relay I3BKRGEX closed	The synch check relay I3BKRGXS, known as K25A, on TTUR is suspect; also the cabling between VTUR and TTUR may be at fault.
51	L3BKRGES – Auto Synch Relay is Slow. The auto synchronization algorithm has detected that the auto synch relay I3BKRGES had not closed by two cycle times after the command I25 was given	The Auto synch relay I3BKRGES also known as K25, on TTUR is suspect; also the cabling between VTUR and TTUR may be at fault.
52-53	Breaker # Slower than Adjustment Limit Allows. Breaker 1 or 2 close time was measured to be slower	The breaker is experiencing a problem, or the operator should
	than the auto synch algorithms adaptive close time adjustment limit allows	consider changing the configuration (both nominal close time and self- adaptive limit in ms can be configured).
54		(both nominal close time and self- adaptive limit in ms can be
54 55	adjustment limit allows Synchronization Trouble - K25 Relay Locked Up. The auto synchronization algorithm has determined that the auto synch relay I3BKRGES, also known as K25, is locked up. Auto synch will not be possible until the relay is	(both nominal close time and self- adaptive limit in ms can be configured). K25 on TTUR is most likely stuck
	adjustment limit allows Synchronization Trouble - K25 Relay Locked Up. The auto synchronization algorithm has determined that the auto synch relay I3BKRGES, also known as K25, is locked up. Auto synch will not be possible until the relay is replaced Card and Configuration File Incompatibility. You are attempting to install a VTUR board that is not compatible	(both nominal close time and self- adaptive limit in ms can be configured). K25 on TTUR is most likely stuck closed, or the contacts are welded.
55	adjustment limit allows Synchronization Trouble - K25 Relay Locked Up. The auto synchronization algorithm has determined that the auto synch relay I3BKRGES, also known as K25, is locked up. Auto synch will not be possible until the relay is replaced Card and Configuration File Incompatibility. You are attempting to install a VTUR board that is not compatible with the VTUR TRE file you have installed Term Board on J5X and Config File Incompatibility. VTUR detects that the terminal board that is connected to	(both nominal close time and self- adaptive limit in ms can be configured). K25 on TTUR is most likely stuck closed, or the contacts are welded. Install the correct TRE file from the factory
55 56	adjustment limit allows Synchronization Trouble - K25 Relay Locked Up. The auto synchronization algorithm has determined that the auto synch relay I3BKRGES, also known as K25, is locked up. Auto synch will not be possible until the relay is replaced Card and Configuration File Incompatibility. You are attempting to install a VTUR board that is not compatible with the VTUR TRE file you have installed Term Board on J5X and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J3 and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J3 and Config File Incompatibility.	 (both nominal close time and self- adaptive limit in ms can be configured). K25 on TTUR is most likely stuck closed, or the contacts are welded. Install the correct TRE file from the factory Check your configuration.
55 56 57	adjustment limit allows Synchronization Trouble - K25 Relay Locked Up. The auto synchronization algorithm has determined that the auto synch relay I3BKRGES, also known as K25, is locked up. Auto synch will not be possible until the relay is replaced Card and Configuration File Incompatibility. You are attempting to install a VTUR board that is not compatible with the VTUR TRE file you have installed Term Board on J5X and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J3 and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J3 and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J4 and Config File Incompatibility. VTUR detects that the terminal board that is configured Term Board on J4 and Config File Incompatibility.	 (both nominal close time and self- adaptive limit in ms can be configured). K25 on TTUR is most likely stuck closed, or the contacts are welded. Install the correct TRE file from the factory Check your configuration. Check your configuration.

60	Term. Board TTUR and card VTUR Incompatibility. VTUR detects that the TTUR connected to it is an incompatible hardware revision	The TTUR or VTUR must be changed to a compatible combination.
61	TRPL or TRPS Solenoid Power Bus "A" Absent	Cabling problem or solenoid power source
62	TRPL or TRPS Solenoid Power Bus "B" Absent	Cabling problem or solenoid power source
63	TRPL or TRPS Solenoid Power Bus "C" Absent	Cabling problem or solenoid power source
64-66	TRPL/S J4 Solenoid # Voltage mismatch. The voltage feedback disagrees with the PTR or ETR feedback	PTR or ETR relays, or defective feedback circuitry
128-223	Logic Signal # Voting mismatch. The identified signal from this board disagrees with the voted value	A problem with the input. This could be the device, the wire to the terminal board, the terminal board, or the cable.
224-251	Input Signal # Voting mismatch, Local #, Voted #. The specified input signal varies from the voted value of the signal by more than the TMR Diff Limit	A problem with the input. This could be the device, the wire to the terminal board, the terminal board, or the cable.



+1 540 387 7000 www. Geindustrial.com GE Industrial Systems

General Electric Company 1501 Roanoke Blvd. Salem, VA 24153-6492 USA



GE Industrial Systems

VVIB Vibration/Position Board

These instructions do not purport to cover all details or variations in equipment, nor to provide for every possible contingency to be met during installation, operation, and maintenance. The information is supplied for informational purposes only, and GE makes no warranty as to the accuracy of the information included herein. Changes, modifications, and/or improvements to equipment and specifications are made periodically and these changes may or may not be reflected herein. It is understood that GE may make changes, modifications, or improvements to the equipment referenced herein or to the document itself at any time. This document is intended for trained personnel familiar with the GE products referenced herein.

GE may have patents or pending patent applications covering subject matter in this document. The furnishing of this document does not provide any license whatsoever to any of these patents. All license inquiries should be directed to the address below. If further information is desired, or if particular problems arise that are not covered sufficiently for the purchaser's purpose, the matter should be referred to:

GE Industrial Systems Post Sales Service 1501 Roanoke Blvd. Salem, VA 24153-6492 USA Phone: + 1 888 GE4 SERV (888 434 7378, United States) + 1 540 378 3280 (International) Fax: + 1 540 387 8606 (All)

("+" indicates the international access code required when calling from outside the USA)

This document contains proprietary information of General Electric Company, USA and is furnished to its customer solely to assist that customer in the installation, testing, operation, and/or maintenance of the equipment described. This document shall not be reproduced in whole or in part nor shall its contents be disclosed to any third party without the written approval of GE Industrial Systems.

GE PROVIDES THE FOLLOWING DOCUMENT AND THE INFORMATION INCLUDED THEREIN AS IS AND WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO ANY IMPLIED STATUTORY WARRANTY OF MERCHANTABILITY OR FITNESS FOR PARTICULAR PURPOSE.

Issue date: 2002-06-30

© 2002 by General Electric Company, USA. All rights reserved

Section	Page
Functional Description	
Installation	
Operation	
Features	
Specifications	7
Diagnostics	
DVIB Vibration Terminal Board	
Installation	
I/O Board Alarms	

Functional Description

If desired a Bently Nevada 3500 monitoring system can be cabled into the terminal board to permanently monitor turbine vibration. The Mark VI system uses Bently Nevada probes for shaft vibration monitoring. Up to 14 probes connect directly to the TVIB terminal board, two of which can be cabled to the VVIB board. The signals are processed by the VVIB board, and the digitized displacement and velocity signals are sent over the VME bus to the controller. Also the type 2 terminal board (H2A) has BNC connectors allowing portable vibration data gathering equipment to be plugged in for predictive maintenance purposes.